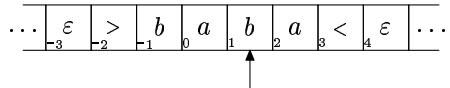


**Introduction to Theoretical Computer Science**  
**Tutorial 10**  
**Solutions to the demonstration problems**

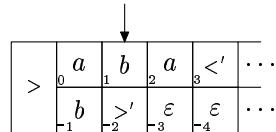
4. **Problem:** Extend the notion of a Turing machine by providing the possibility of a two-way infinite tape. Show that nevertheless such machines recognize exactly the same languages as the standard machines whose tape is only one-way infinite.

**Solution:** A Turing machine with a two-way infinite tape works otherwise in a same way than a standard machine except that the position of the tape start symbol ( $>$ ) is not fixed and it can move in a same way than the end symbol ( $<$ ). The tape positions are indexed by the set  $\mathbb{Z}$  of integers where 0 denotes the initial position of  $>$ .

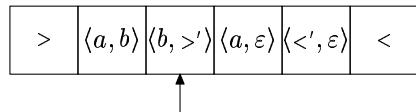
We can simulate such a Turing machine by a two-track one-way Turing machine. Conceptually, we divide the tape into two parts: upper and lower. The upper part holds the two-way tape cells  $i \geq 0$  and the lower part cells  $i < 0$ . For example, a two-way tape:



is expressed as a one-way tape:



In practice the construction of two tracks is done by replacing the alphabet  $\Sigma$  by a new alphabet  $\Sigma' = (\Sigma \cup \{\langle', \rangle'\}) \times (\Sigma \cup \{\langle', \rangle'\})$ . Each symbol of  $\Sigma'$  thus denotes two symbols of  $\Sigma$ . The symbols  $\{\langle', \rangle'\}$  are new symbols that denote the start and end symbols of the original tape. So, the above example is expressed as:



We still need a way to decide which tape-half is used. The easiest way to do this is to define a mirror image state  $q'$  for each state  $q$ . When the machine is in state  $q$ , it examines only the upper track when it decides what move to take next (tape head is on right side of the tape). Similarly, in state  $q'$  it examines only the lower symbol (tape head is on the left side). Since the lower tape is in a reversed order, all tape head moving instructions have to be also reversed.

The formal definition of this construction is presented in an appendix.

5. **Problem:** Show that Turing machines whose tape alphabet contains at most two symbols in addition to the input symbols are capable of recognising exactly the same languages as the standard machines.

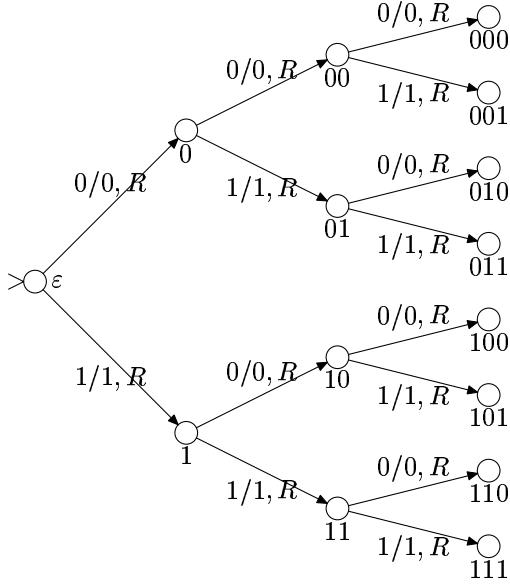
**Solution:**

Let  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{\text{acc}}, q_{\text{rej}})$  be a Turing machine such that  $|\Gamma - \Sigma| > 2$ . We want to construct a machine  $M'$  such that  $\Gamma' = \{0, 1\}$ . Let  $\Gamma = \{a_1, \dots, a_n\}$ . The basic idea of the construction is to identify the elements of  $\Gamma$  with the integers  $\{1, \dots, n\}$  and represent them as  $k$ -bit integers, where  $k = \lceil \log_2(|\Gamma|) \rceil$ . In other words, each element of  $M$ 's tape

alphabet is replaced with  $k$  bits. For example, suppose that  $N = 3$  and the tape has the input  $a_1a_2a_3$ . In this case the encoding is:

$$> \boxed{a_1} \boxed{a_2} \boxed{a_3} < \Rightarrow > \boxed{0} \boxed{1} \boxed{1} \boxed{0} \boxed{1} \boxed{1} <$$

The transition function of  $M'$  is defined so that for each step of  $M$ ,  $M'$  does first  $k$  steps where it first decides what symbol of  $\Gamma$  is encoded in the tape cells to the right of the read/write head. This can be done using a Turing machine that reads  $k$  symbols from the tape while moving its head to right at each step and that remembers the input in its states. For example, if  $k = 3$ , then the following Turing machine may be used:



If the machine ends in the state 011, then the input symbol is  $a_3$  since  $011_2 = 3_{10}$ . The symbol that is written to the tape is similarly done using  $k$  different transitions. Finally, the tape head is moved  $k$  steps to the correct direction.

#### Appendix: the formalisation of solution 4

Let  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{\text{acc}}, q_{\text{rej}})$  be a two-way tape Turing machine. Define a standard Turing machine  $M'$  as follows:

$$\begin{aligned} M' &= (Q', \Sigma', \Gamma', \delta', q_0, q_{\text{acc}}, q_{\text{rej}}) \\ Q' &= Q \cup \{q' \mid q \in Q\} \\ \Sigma' &= (\Sigma \cup \{\langle , \rangle\}) \times (\Sigma \cup \{\langle , \rangle\}) \\ \Gamma' &= (\Gamma \cup \{\langle , \rangle\}) \times (\Gamma \cup \{\langle , \rangle\}) \end{aligned}$$

The transition function  $\delta'$  is defined as follows:

$$\begin{aligned} \delta' &= \{(q_1, \langle a, \gamma \rangle, q_2, \langle b, \gamma \rangle, \Delta) \mid (q_1, a, q_2, b, \Delta) \in \delta, \gamma \in \Gamma'\} \\ &\quad \cup \{(q_1, \langle \sigma', \gamma \rangle, q_2, \langle b, \gamma \rangle, \Delta) \mid (q_1, \sigma, q_2, b, \Delta) \in \delta, \gamma \in \Gamma', \sigma \in \{\langle, \rangle\}\} \\ &\quad \cup \{(q'_1, \langle \gamma, a \rangle, q'_2, \langle \gamma, b \rangle, \bar{\Delta}) \mid (q_1, a, q_2, b, \Delta) \in \delta, \gamma \in \Gamma'\} \\ &\quad \cup \{(q', \langle \gamma, a \rangle, q_{\text{end}}, \langle \gamma, b \rangle, \bar{\Delta}) \mid (q, a, q_{\text{end}}, b, \Delta) \in \delta, q_{\text{end}} \in \{q_{\text{acc}}, q_{\text{rej}}\}, \gamma \in \Gamma'\} \\ &\quad \cup \{(q'_1, \langle \gamma, \bar{\sigma}' \rangle, q'_2, \langle \gamma, b \rangle, \bar{\Delta}) \mid (q_1, \sigma, q_2, b, \Delta) \in \delta, \gamma \in \Gamma', \sigma \in \{\langle, \rangle\}\} \\ &\quad \cup \{(q, \rangle, q', \rangle, R), (q', \rangle, q, \rangle, R) \mid q \in Q\}, \end{aligned}$$

where  $\bar{L} = R$ ,  $\bar{R} = L$ ,  $\bar{\langle} = \rangle$  and  $\bar{\rangle} = \langle$ .